

Lumped Circuit Model for Eddy Currents in Tokamak Passive Structures

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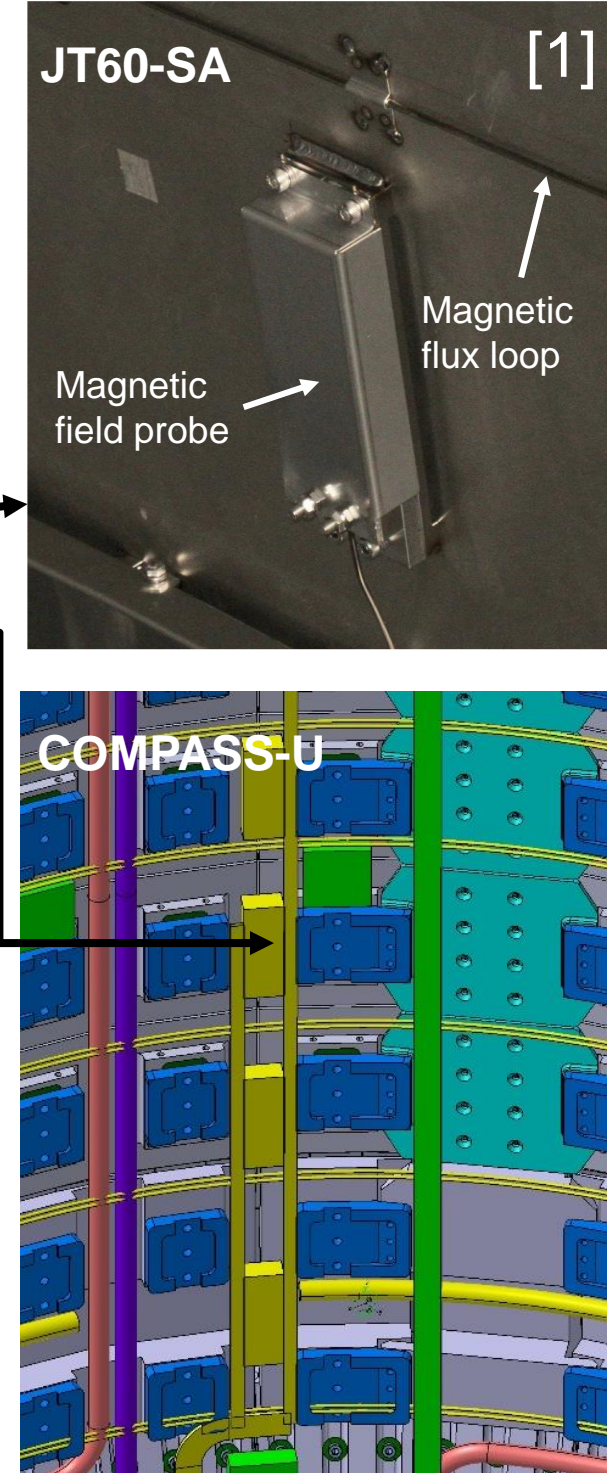
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1 Introduction

- Measurements of **local magnetic fields** and **magnetic fluxes** in tokamak → **plasma control feedback** + **equilibrium reconstruction**.
- Magnetic sensors:
 - Installed on vacuum vessel or other conductive surface
 - Protected by complex geometry metal elements
- Changes in magnetic signal affected by **eddy currents** induced in the vicinity.
- Necessary to evaluate this effect for plasma control.

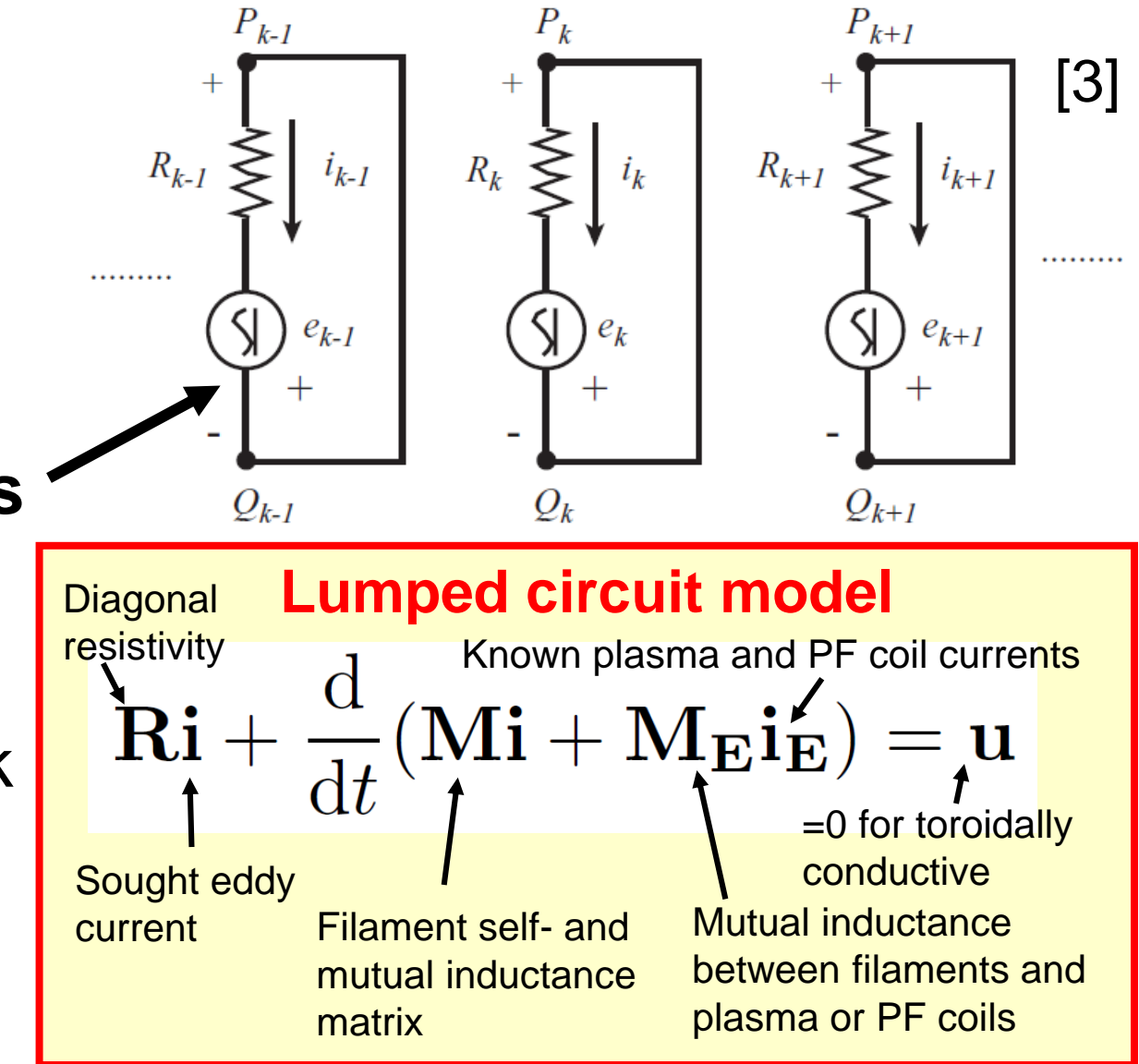
In this work:

- Ready-to-use model based on **lumped circuit approach** is presented and compared to a more sophisticated Ansys model.
- Provided an example of the model use in **assessment of magnetic sensor positions** in COMPASS-U.



2 Lumped circuit eddy model

- Tokamak plasma equilibrium – toroidally symmetric → so are **fields** and **eddy currents**.
- For non-axisymmetric effects see our paper [2].
- Vacuum vessel (VV)** → approximated by **series of toroidal filaments**. These are **coupled to plasma, tokamak PF coils** and **to each other**.
- Method well described in [3], popular in tokamak community [3-6]. First degree ODE.
- Drawback – PF coils and plasma current are **assumed** not to be affected by eddy currents.

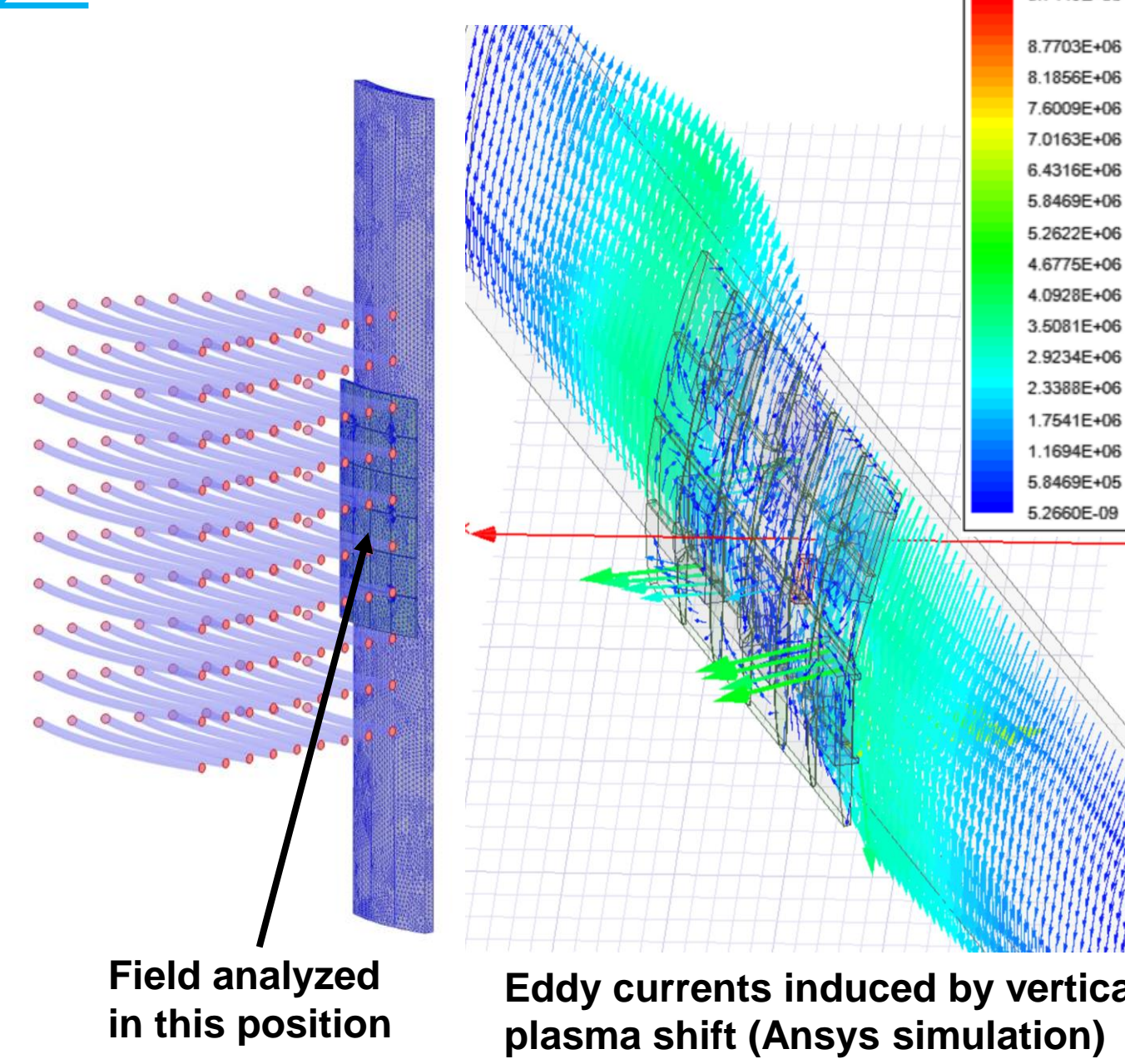


3 Model validation with Ansys

Ansys Maxwell software – finite element analysis – 3D calculation of eddy currents in fusion devices [7] (mechanical forces).

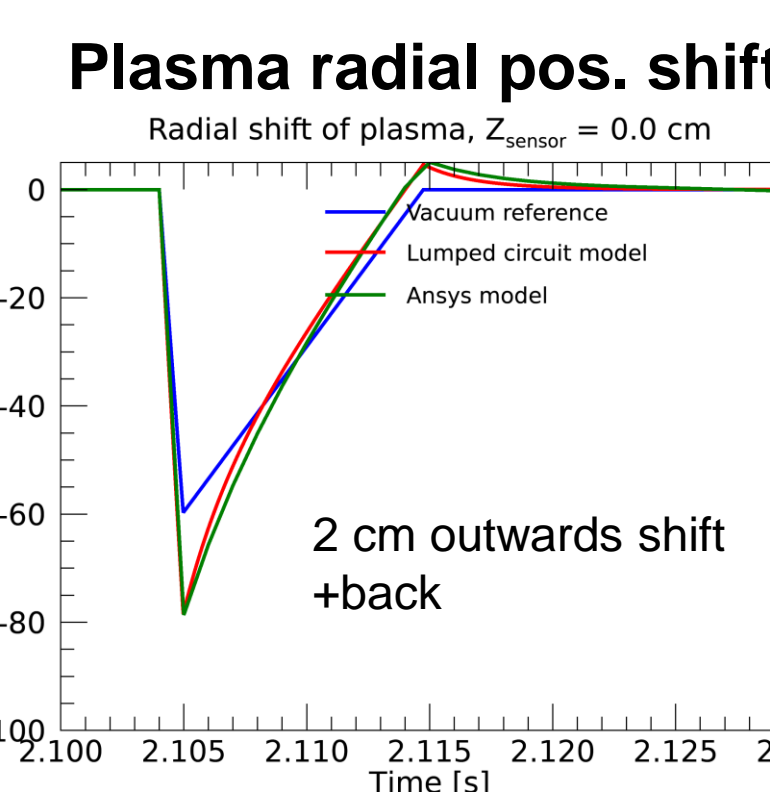
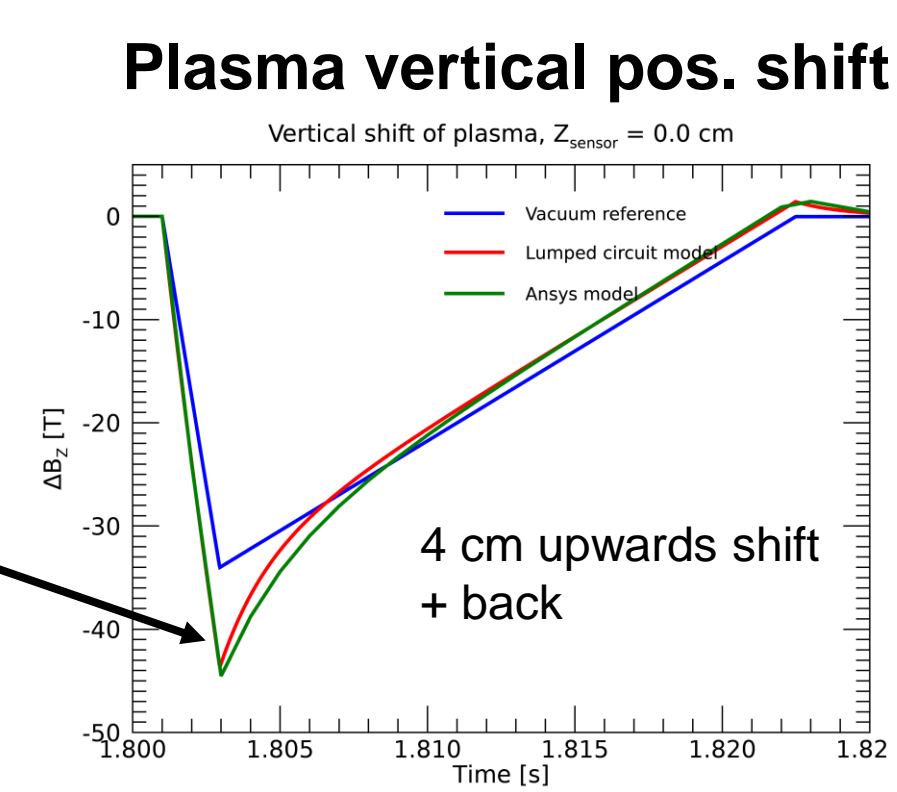
3.1 Vacuum vessel model

- VV** – 1/16 periodic **cylindrical segment**. In this work effect of 3D PFC elements is neglected.
- Plasma** – 9x10 filaments of independent currents – represented COMPASS-U discharge 6409 I_{plasma} flat-top phase.
- Investigated **vertical and radial shift** of whole plasma column at **2 cm/ms** speed.



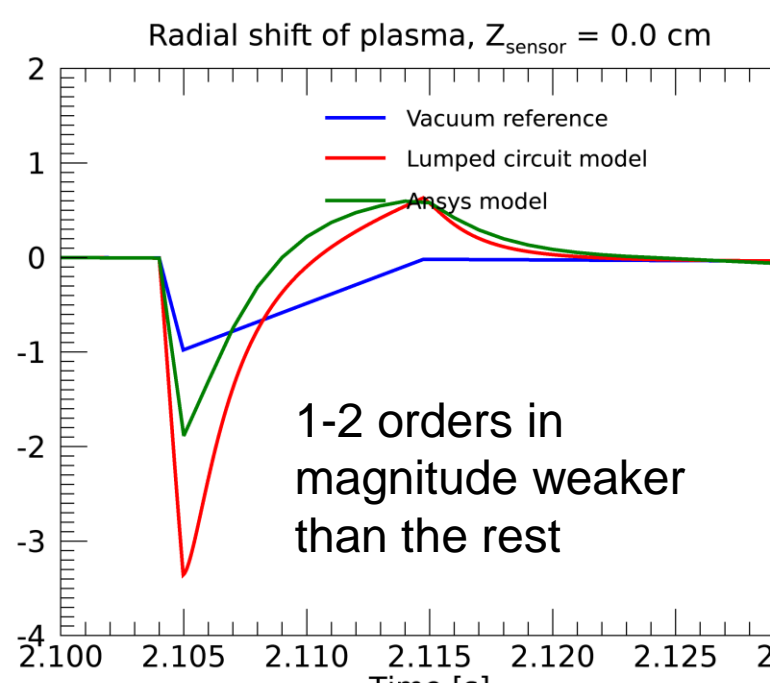
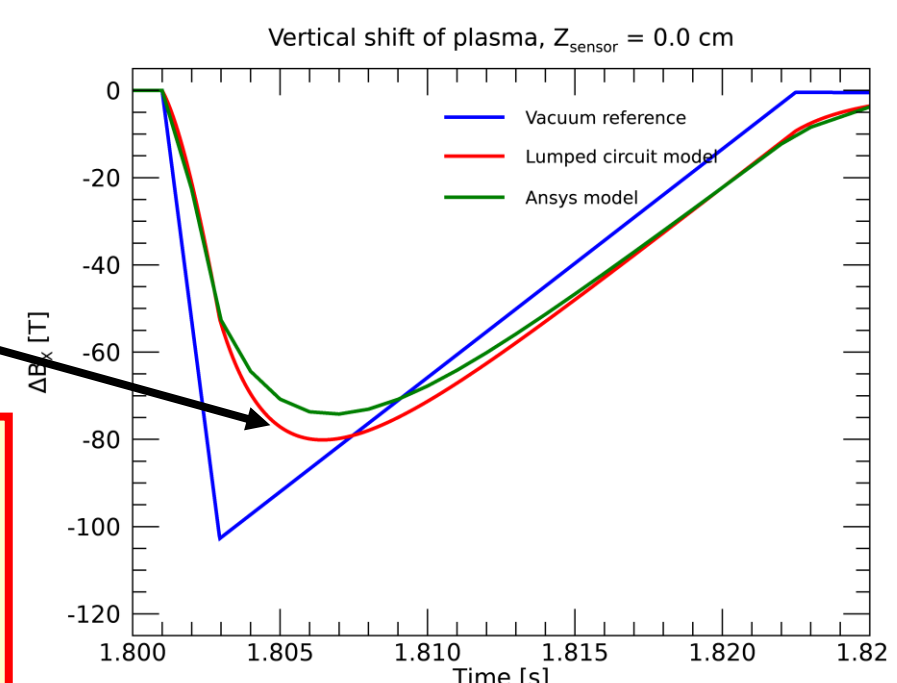
Vertical field component B_z :

- Good agreement between lumped circuit and Ansys.
- Amplified by eddy currents.



Normal field component B_x :

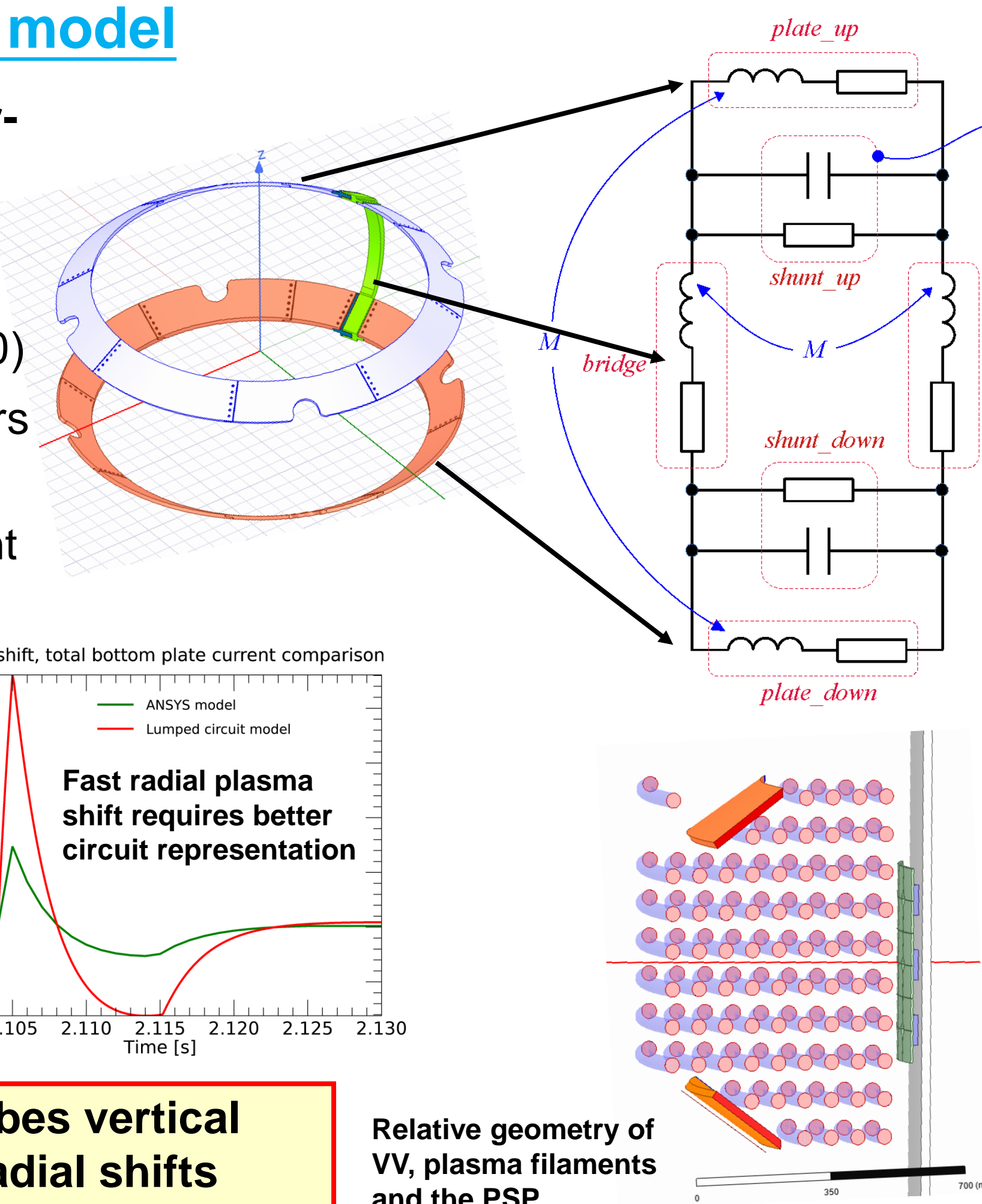
- Non-negligible only for vertical plasma movement. Good model agreement.
- Attenuated by eddy currents.



Agreement between lumped circuit model and Ansys for toroidally symmetric structures.

3.2 Plasma stabilizing plate model

- COMPASS-U will feature **counter-wound plasma stabilizing plate** structure.
- Coupled current circuit introduced into the model (equivalent to $\mathbf{u} \neq 0$)
- Bridge included as well. Capacitors only present in the Ansys model
- Validation – total plate eddy current comparison between both models:



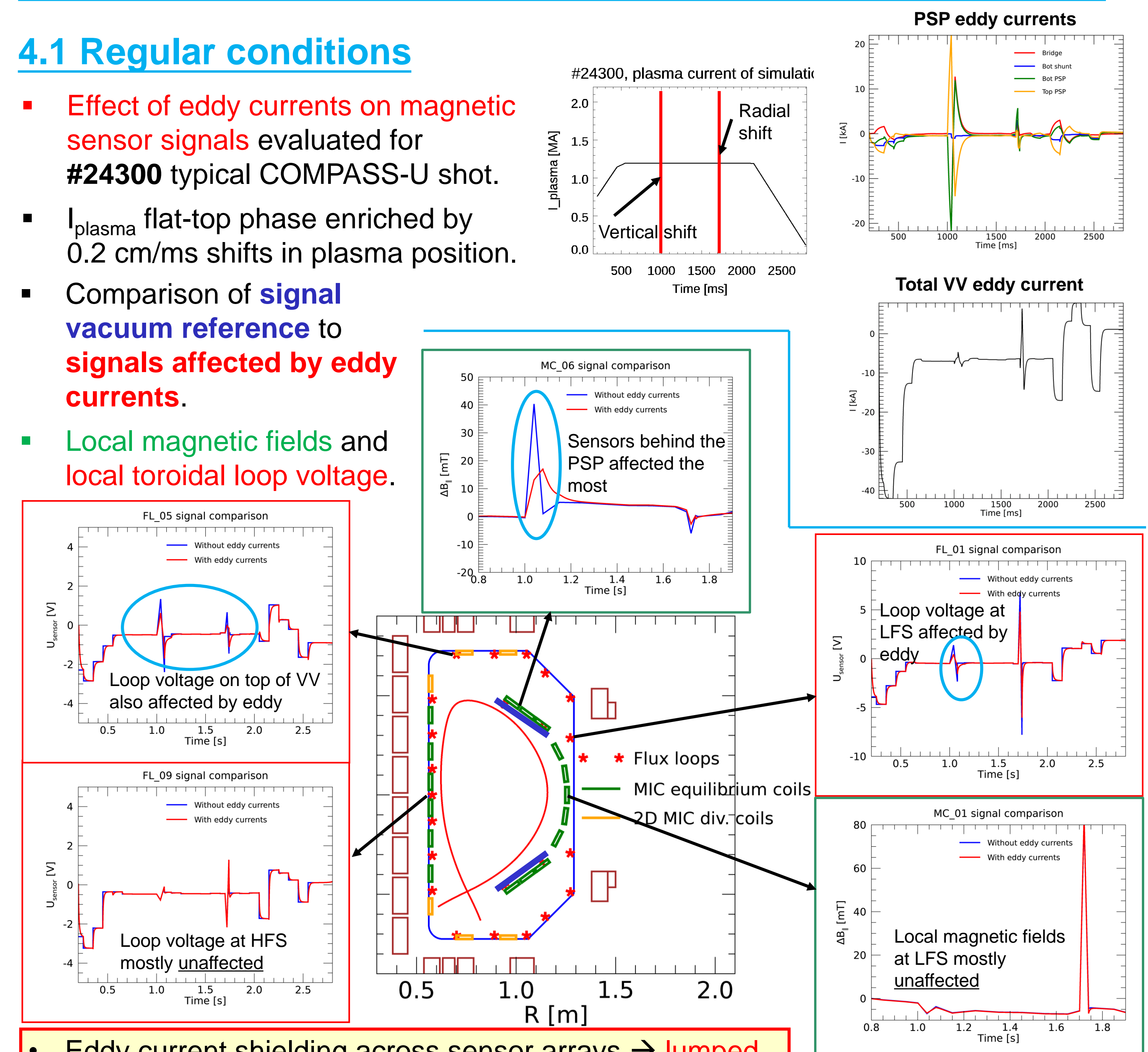
Lumped circuit model of PSP describes vertical plasma position shifts well. Fast radial shifts insufficiently described with the present circuit.

Relative geometry of VV, plasma filaments and the PSP

4 Interpretation of tokamak magnetic sensor signal

4.1 Regular conditions

- Effect of eddy currents on magnetic sensor signals evaluated for **#24300** typical COMPASS-U shot.
- I_{plasma} flat-top phase enriched by 0.2 cm/ms shifts in plasma position.
- Comparison of **signal vacuum reference** to **signals affected by eddy currents**.
- Local magnetic fields** and **local toroidal loop voltage**.

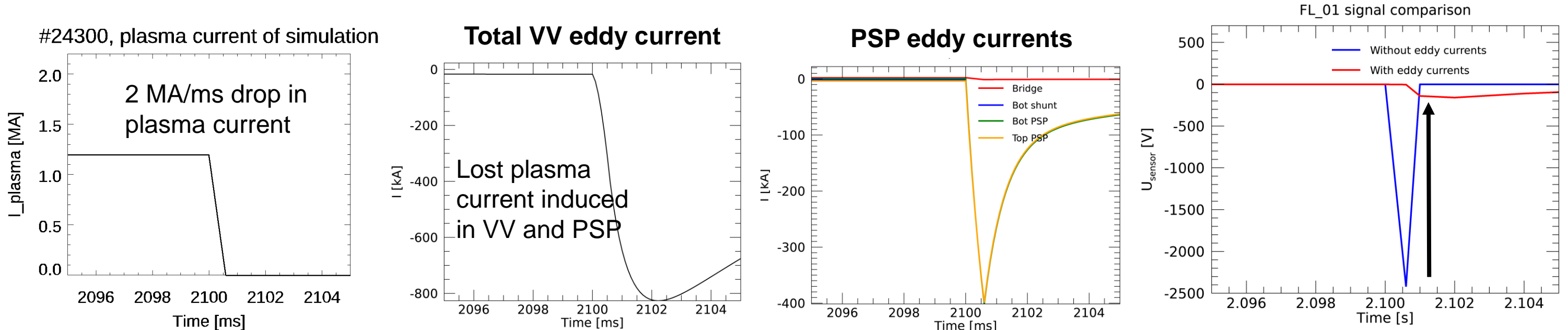


- Eddy current shielding across sensor arrays → **lumped circuit model necessary for equilibrium reconstruction**.
- Optimal sensors for **fast plasma feedback** – **HFS flux loops** and **LFS magnetic coils**.

4.2 Disruption voltages

- Discharge disruption – rapid disappearance of ~1-2 MA
- ~10⁰ kV in flux loops → not acceptable for wire ins. material.

Lumped circuit model predicts ~10⁻¹ kV peaks only, thanks to the eddy current attenuation. → Acceptable for wiring.



5 Summary

- Eddy currents** induced in tokamak conducting **structures** can significantly affect **magnetic field and flux measurements** in their vicinity.
- Lumped circuit model** performs well to quantify this effect – validated by Ansys model in this work. However, calculation of currents that force themselves across shunt resistors of PSP need although improvement in PSP circuit representation.
- Model shows **that the least affected sensors** by axisymmetric eddy current attenuation are **LFS midplane coils** and **HFS flux loops** → optimal choice of sensors for fast feedback plasma control algorithms.

Acknowledgements

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